PROGRESS REPORT

For

AUTOMATIC STEREO CORRELATOR

SC 1305

"Construction of Breadboard System of an Automatic Stereo Correlator and Evaluation of the Performance Capabilities of such a System."

Period Covered:

January 1965 - February 1965

Date:

16 February 1965

Job No.:

SC 1305

Document No.:

OD-115

This is the sixth monthly progress report.

TASK OBJECTIVE

To manufacture a breadboard and to conduct sufficient tests to determine the performance capabilities inherent in a system of automatic stereo correlation as described in the 552 MSC proposal.

CURRENT STATUS OF WORK

Electronic

- Modification of the main channel amplifier to accommodate large signal levels has been completed.
- 2) Modification of the intensity channel preamplifier to accomodate large signal levels has commenced.
- 3) The servo amplifiers have been connected to their respective motors and tested.
- 4) The limit switches for the X-Y drive have been installed and adjusted.
 - 5) An interconnection drawing has been made.

Opto-Mechanical

- 1) The X-Y drive table and the servoed scan head have been integrated.
- 2) Rework to the 0 axis should be completed by the 16th of February.

 See "Problem Areas Encountered" for details.
 - 3) The zoom mechanism has been assembled and tested.

PROBLEM AREAS ENCOUNTERED

- 1) It was determined that the use of a fiber optic cable without image enhancement would be unsatisfactory. Rework was required to avoid the use of a fiber optic cable. It was necessary to combine the opto-mechanical assemblies that were to be coupled by the fiber optic cable into a single assembly and to provide different means for angular correction.
- 2) It proved impractical to continue electrical tests during the entire period of rework and mechanical integration.

DOCUMENTATION OF VERBAL COMMITMENTS AND/OR AGREEMENTS

None have been made.

PROJECTED WORK FOR NEXT PERIOD

Completion of the Project, consisting of:

- 1) Integrate servo functions (X, Y, 0, M, and intensity) one at a time and evaluate interactions.
 - 2) Check servo performance and adjust gain, damping and phasing.
 - 3) Evaluate total system performance and write final report.
 - 4) Update drawings for record purposes.